Proyecciones Journal of Mathematics Vol. 42, N<sup>o</sup> 1, pp. 53-63, February 2023. Universidad Católica del Norte Antofagasta - Chile



# Jordan product and fixed points preservers

M. Elhodaibi Labo LIABM, Morocco and S. Elouazzani Labo LIABM, Morocco Received : March 2022. Accepted : August 2022

#### Abstract

Let  $\mathcal{B}(X)$  be the space of all bounded linear operators on complex Banach space X. For  $A \in \mathcal{B}(X)$ , we denote by F(A) the subspace of all fixed points of A. In this paper, we study and characterize all surjective maps  $\phi$  on  $\mathcal{B}(X)$  satisfying

 $F(\phi(T)\phi(A) + \phi(A)\phi(T)) = F(TA + AT)$ 

for all  $A, T \in B(X)$ .

Keywords: Fixed points; Jordan product; Preserver.

Subject: 47A10, 47A11, 47B49.

### 1. Introduction

In the following, X is a complex Banach space, and  $\mathcal{B}(X)$  denotes the space of all bounded linear operators on X. Let  $X^*$  be the dual space of X. Given a vector  $x \in X$  and a linear functional  $f \in X^*$ , the rank at most one operator,  $x \otimes f$ , defined by  $(x \otimes f)z = f(z)x$  for all  $z \in X$ . Note that

(1.1)  $x \otimes f$  is nilpotent if and only if f(x) = 0,

and

(1.2) 
$$x \otimes f$$
 is idempotent if and only if  $f(x) = 1$ .

We denote by  $\mathcal{F}_1(X)$  and  $\mathcal{N}_1(X)$  the set of all rank at most one operators and the set of all rank one nilpotent operators, respectively. For any subspace  $Y \subset X$ , the dimension of Y will be denoted by dim Y. For every operator  $T \in \mathcal{B}(X)$ , let N(T) be the kernel of T, and R(T) be its range. For an operator  $A \in \mathcal{B}(X)$ , a vector  $x \in X$  is a fixed point of A if Ax = x. Let F(A) be the set of all fixed points of A. The lattice of A, Lat(A), is the set of all invariant subspaces of A. Recall that  $F(A) \in Lat(A)$  for every  $A \in \mathcal{B}(X)$ . Recall also that the set of fixed points of rank one operator is given by

$$F(x \otimes f) = \begin{cases} span\{x\} & \text{if } x \otimes f \text{ is idempotent,} \\ \{0\} & \text{if } x \otimes f \text{ is not idempotent.} \end{cases}$$

The study of maps on operators or matrices that leave some properties invariant, is the most active problems in the last decades, see for instance [1, 3, 5, 6, 8].

Recently, many authors have studied the subspace of fixed points preservers. For example, in [9] A. Taghavi and R. Hosseinzadeh characterized all surjective maps on  $\mathcal{B}(X)$  preserving the dimension of the vector space containing of all fixed points of products of operators, they showed that if X is a complex Banach space with dim  $X \ge 3$  and  $\phi : \mathcal{B}(X) \longrightarrow \mathcal{B}(X)$  is a surjective map satisfies

$$\dim F(\phi(A)\phi(B)) = \dim F(AB)$$

for all  $A, B \in \mathcal{B}(X)$ , then there exists an invertible operator  $S \in \mathcal{B}(X)$ such that  $\phi(A) = \pm SAS^{-1}$  for all  $A \in \mathcal{B}(X)$ . In [10] A. Taghavi, R. Hosseinzadeh and V. Darvish described the forms of surjective maps  $\phi$  on  $\mathcal{B}(X)$  satisfying

$$F(\phi(A)\phi(B)\phi(A)) = F(ABA)$$

for all  $A, B \in \mathcal{B}(X)$ , where X is a complex Banach space with dim  $X \ge 3$ , they proved that there exists a nonzero scalar  $\alpha \in \mathbb{C}$  with  $\alpha^3 = 1$  such that  $\phi(A) = \alpha A$  for every  $A \in \mathcal{B}(X)$ . In [2] Y. Bouramdane et al. proved the previous result for the generalized product of operators.

This paper is motivated by the ideas from [2], but the proofs of our main results require new agruments. The statements of our main result can be stated as follows.

**Theorem 1.** Let X be a complex Banach space with dim  $X \ge 4$  and  $\phi : \mathcal{B}(X) \longrightarrow \mathcal{B}(X)$  be a surjective map. Then the following assertions are equivalent.

(i) For all  $T, S \in \mathcal{B}(X)$ , we have

(1.3) 
$$F(\phi(T)\phi(S) + \phi(S)\phi(T)) = F(TS + ST).$$

(ii) There exists a nonzero scalar  $\alpha \in \mathbf{C}$  with  $\alpha^2 = 1$  such that  $\phi(T) = \alpha T$  for all  $T \in \mathcal{B}(X)$ .

## 2. Preliminaries and Notations

To formulate the next lemma, we use this notation

$$\mathcal{F}_{1,\sqrt{2}}(X) := \{ x \otimes f : x \in X \text{ and } f \in X^* \text{ with } f(x) = \frac{1}{\sqrt{2}} \}.$$

In the following lemma, we will give a condition for two operators to be the same.

**Lemma 1.** Let A and B be non-scalar operators. The following statements are equivalent.

(i) A = B.

(ii) 
$$F(AT + TA) = F(BT + TB)$$
 for all  $T \in \mathcal{F}_{1,\sqrt{2}}(X)$ .

**Proof.** Since  $(i) \Longrightarrow (ii)$  is obvious, we need only to prove the implication  $(ii) \Longrightarrow (i)$ . Let us set R = AT + TA and S = BT + TB. Assume that  $A \neq B$ , so we shall distinguish two cases.

**Case 1.** x, Ax and Bx are linearly independent for certain nonzero vector  $x \in X$ . We will discuss two cases.

**Case 1.1.** If x, Ax and  $A^2x$  are linearly independent. It follows that there exists  $f \in X^*$  such that  $f(x) = f(A^2x) = \frac{1}{\sqrt{2}}$  and  $f(Ax) = 1 - \frac{1}{\sqrt{2}}$ . Hence we get that  $x + Ax \in F(R) = F(S) \subset span\{x, Bx\}$ , this is a contradiction.

**Case 1.2.** If not, then there exist  $a, b \in \mathbb{C}$  such that  $A^2x = aAx + bx$ . Let  $f \in X^*$  such that  $f(x) = \frac{1}{\sqrt{2}}$  and  $f(Ax) = \mu$  with  $-\sqrt{2}\mu^2 + (a + 2\sqrt{2})\mu + (\frac{b}{\sqrt{2}} - \sqrt{2}) = 0$ . Consider an operator  $T \in \mathcal{B}(X)$  such that  $T = x \otimes f$ . Hence we have

(2.1) 
$$R(\sqrt{2}(1-\mu)x + Ax) = (-\sqrt{2}\mu^2 + (a+\sqrt{2})\mu + \frac{b}{\sqrt{2}})x + Ax$$
$$= \sqrt{2}(1-\mu)x + Ax.$$

Thus by (2.1) we obtain that  $\sqrt{2}(1-\mu)x + Ax \in F(R) = F(S) \subset span\{x, Bx\}$ , a contradiction.

**Case 2.** x, Ax and Bx are linearly dependent for all  $x \in X$ . Lemma 2.4 in [7] tell us that there exist  $\alpha, \lambda \in \mathbb{C}$  such that  $B = \lambda A + \alpha I$ . By hypothesis, A is a non-scalar operator, there exists a nonzero vector  $x \in X$  such that Ax and x are linearly independent. On the other hand we have

$$\begin{cases} Rx = f(Ax)x + f(x)Ax \\ RAx = f(A^2x)x + f(Ax)Ax \end{cases} \text{ and } \begin{cases} Sx = \lambda Rx + 2\alpha f(x)x \\ SAx = \lambda RAx + 2\alpha f(Ax)x. \end{cases}$$

We discuss two cases.

**Case 2.1.** If x, Ax and  $A^2x$  are linearly independent for certain  $x \in X$ . Then there exists  $f \in X^*$  such that  $f(x) = f(A^2x) = \frac{1}{\sqrt{2}}$  and  $f(Ax) = 1 - \frac{1}{\sqrt{2}}$ . Hence we get that  $x + Ax \in F(R) = F(S)$ . Since

$$S(x + Ax) = \lambda(x + Ax) + 2\alpha x$$
  
= x + Ax,

we obtain  $\lambda = 1$  and  $\alpha = 0$ .

**Case 2.2.** If x, Ax and  $A^2x$  are linearly dependent for all  $x \in X$ . It follows that there exist  $a, b \in \mathbb{C}$  such that  $A^2x = aAx + bx$ . As in the *Case 1.2*, we can get that  $\sqrt{2}(1-\mu)x + Ax \in F(R) = F(S)$ . On the other hand we have

(2.2) 
$$S(\sqrt{2}(1-\mu)x + Ax) = \lambda(\sqrt{2}(1-\mu)x + Ax) + 2\alpha x \\ = \sqrt{2}(1-\mu)x + Ax,$$

Hence by (2.2) we obtain that  $\lambda = 1$  and  $\alpha = 0$ , as desired. This finishes the proof.

In the next lemma, we characterize rank one non-nilpotent operators by the dimension of fixed points of Jordan porduct of operators.

**Lemma 2.** For a nonzero operator  $A \in \mathcal{B}(X)$ . The following statements are equivalent.

- (i)  $A \in \mathcal{F}_1(X) \setminus \mathcal{N}_1(X)$ .
- (ii)  $dimF(AT + TA) \leq 1$  for all  $T \in \mathcal{B}(X)$ .

**Proof.**  $(i) \Longrightarrow (ii)$  Let  $T \in \mathcal{B}(X)$  be an arbitrary operator, and consider a non-nilpotent operator  $A = x \otimes f$  where  $x \in X$  and  $f \in X^*$ . Note that

$$\begin{cases} (AT + TA)x = f(Tx)x + f(x)Tx\\ (AT + TA)Tx = f(T^2x)x + f(Tx)Tx. \end{cases}$$

Now, if Tx and x are linearly independent, then we have  $x \notin F(AT+TA) \subset span\{x, Tx\}$ . If not, we get that  $F(AT+TA) \subset span\{x\}$ . Hence in both cases, we obtain that  $dimF(AT+TA) \leq 1$ , as desired.

 $(ii) \Longrightarrow (i)$  Suppose that there exists a vector  $x \in X$  such that x, Ax and  $A^2x$  are linearly independent. Let  $T \in \mathcal{B}(X)$  such that

$$Tx = 0$$
,  $TAx = x$  and  $TA^2x = 0$ .

Then

$$(AT + TA)x = x$$
  
(AT + TA)Ax = Ax,

which implies that  $span\{x, Ax\} \subseteq F(AT + TA)$ , a contradiction. Hence x, Ax and  $A^2x$  are linearly dependent for all  $x \in X$ . It follows from lemma 2.4 in [7] that there exists a complex minimal polynomial Q of degree less than 2 such that Q(A) = 0. We will distinguish two cases.

**Case 1.** If  $d^{\circ}(Q) = 1$ , then  $A = \lambda I$  where  $\lambda$  is a nonzero scalar. Consider an operator  $T = \frac{1}{2\lambda}I$ , it follows that AT + TA = I, hence F(AT + TA) = X, a contradiction.

**Case 2.** If  $d^{\circ}(Q) = 2$ , then we discuss the following points.

• If Q admits two single nonzero roots  $\lambda_1, \lambda_2 \in \mathbf{C}$ , then

 $Q(A) = (A - \lambda_1 I) (A - \lambda_2 I)$ . It follows that there exist  $x_1, x_2 \in X$  linearly independent vectors such that  $Ax_1 = \lambda_1 x_1$  and  $Ax_2 = \lambda_2 x_2$ . We choose  $T \in \mathcal{B}(X)$  to be an operator satisfying

$$Tx_1 = \frac{1}{2\lambda_1}x_1$$
 and  $Tx_2 = \frac{1}{2\lambda_2}x_2$ .

Then

(2.3) 
$$\begin{cases} (AT + TA)x_1 = x_1 \\ (AT + TA)x_2 = x_2, \end{cases}$$

Hence by (2.3) we get  $span \{x_1, x_2\} \subset F(AT + TA)$ , a contradiction.

• If Q has a single nonzero root  $\lambda \in \mathbf{C}$ , it follows that  $Q(A) = A(A - \lambda I)$ . If  $dim N(A - \lambda I) = 1$ , then, since  $R(A) \subset N(A - \lambda I)$ , we have  $A \in \mathcal{F}_1(X) \setminus \mathcal{N}_1(X)$ , because if  $A \in \mathcal{N}_1(X)$ , we obtain that  $\lambda = 0$ . Now, if  $dim N(A - \lambda I) \geq 2$ , then there exist  $x_1, x_2 \in X$  linearly independent vectors such that  $Ax_1 = \lambda x_1$  and  $Ax_2 = \lambda x_2$ . Just as before we can get a contradiction.

• If Q admits a double nonzero root  $\lambda \in \mathbf{C}$ , then  $Q(A) = (A - \lambda I)^2$ , and so there exist  $x_1, x_2 \in X$  linearly independent vectors such that  $Ax_1 = \lambda x_1$  and  $Ax_2 = x_1 + \lambda x_2$ . Let  $T \in \mathcal{B}(X)$  satisfying  $Tx_1 = \frac{1}{2\lambda}x_1$  and  $Tx_2 = -\frac{1}{2\lambda^2}x_1 + \frac{1}{2\lambda}x_2$ . Hence, we get that  $span\{x_1, x_2\} \subset F(AT + TA)$ , which is a contradiction.

• If zero is a double root of Q, hence  $Q(A) = A^2$ . If dim N(A) = 1, then, since  $R(A) \subset N(A)$ , we have  $A \in \mathcal{N}_1(X)$ . Let  $A = y \otimes f$  where  $y \in X, f \in X^*$  and f(y) = 0. Consider an operator  $T \in \mathcal{B}(X)$  such that  $(y, Ty, T^2y)$  are linearly independent, f(Ty) = 1 and  $f(T^2y) = 0$ . Hence we obtain that  $span\{y, Ty\} \subset F(AT + TA)$ , this is a contradiction. Now, if  $dimN(A) \geq 2$  and  $dimR(A) \geq 2$ , then there exist  $x_1, x_2, x_3, x_4 \in X$ linearly independent vectors such that  $Ax_1 = 0, Ax_2 = 0, Ax_3 = x_1$  and  $Ax_4 = x_2$ . Take an operator  $T \in \mathcal{B}(X)$  satisfying

$$Tx_1 = x_3, Tx_2 = x_4, Tx_3 = 0$$
 and  $Tx_4 = 0$ .

Thus we get that span  $\{x_1, x_2, x_3, x_4\} \subset F(AT + TA)$ , a contradiction. This ends the proof.

#### 3. Proof of Theorem 1

The implication  $(ii) \Longrightarrow (i)$  is obvious. We only need to show that  $(i) \Longrightarrow (ii)$ . Let us discuss the several steps.

**Step 1.** For every  $A \in \mathcal{B}(X)$ , we have  $\phi(A) = 0$  if and only if A = 0.

If  $\phi(0) = \alpha I$ , then  $F(2\alpha T) = \{0\}$  for all  $T \in \mathcal{B}(X)$ , thus  $\alpha = 0$ . Assume that  $\phi(0) \neq 0$ . Let  $x \in X$  be a nonzero vector such that  $\phi(0)x$  and x are linearly independent. It follows that there is a linear functional  $f \in X^*$ such that f(x) = 0 and  $f(\phi(0)x) = 1$ . Since  $\phi$  is surjective, we take an operator  $T \in \mathcal{B}(X)$  such that  $\phi(T) = x \otimes f$ . This implies that

$$\{0\} = F(0T + T0) = F(\phi(0)\phi(T) + \phi(T)\phi(0)) = F(\phi(0)x \otimes f + x \otimes f\phi(0)).$$

On the other hand we have

$$(\phi(0)x \otimes f + x \otimes f\phi(0))x = f(x)\phi(0)x + f(\phi(0)x)x$$
  
= x,

and so  $x \in F(\phi(0)x \otimes f + x \otimes f\phi(0))$ , a contradiction. Thus  $\phi(0) = 0$ .

Next, assume that  $\phi(A) = 0$  for certain  $A \in \mathcal{B}(X)$ . If  $A = \beta I$ , then we have  $F(2\beta T) = \{0\}$  for all  $T \in \mathcal{B}(X)$ , hence  $\beta = 0$ . Suppose that  $A \neq 0$ , it follows that there is a nonzero vector  $x \in X$  such that Ax and x are linearly independent. Then there exists  $f \in X^*$  such that f(x) = 0 and f(Ax) = 1. For  $T = x \otimes f$ , we have

(3.1) 
$$\{0\} = F(\phi(x \otimes f)\phi(A) + \phi(A)\phi(x \otimes f))$$
$$= F(x \otimes fA + Ax \otimes f).$$

Since

(3.2) 
$$(x \otimes fA + Ax \otimes f)x = f(x)Ax + f(Ax)x \\ = x,$$

Hence by (3.1) and (3.2) we get a contradiction. Therefore A = 0.

**Step 2.** For every operator  $R \in \mathcal{B}(X)$ , we have  $\phi(R) \in \mathcal{F}_1(X) \setminus \mathcal{N}_1(X)$  if and only if  $R \in \mathcal{F}_1(X) \setminus \mathcal{N}_1(X)$ .

By using lemma 2 and the surjectivity of  $\phi$ , we can easly get that  $\phi$  preserves non-nilpotent rank one operators in both directions.

**Step 3.** There exists a nonzero scalar  $\alpha \in \mathbf{C}$  with  $\alpha^2 = 1$  such that  $\phi(A) = \alpha A$  for every  $A \in \mathcal{F}_{1,\sqrt{2}}(X)$ .

Let  $x \in X$  and  $f \in X^*$  such that  $f(x) = \frac{1}{\sqrt{2}}$ . From Step 2, there exist  $y \in X$  and  $g \in X^*$  such that  $\phi(x \otimes f) = y \otimes g$ . Hence we have

$$span\{x\} = F(\frac{2}{\sqrt{2}}x \otimes f)$$
  
=  $F(x \otimes fx \otimes f + x \otimes fx \otimes f)$   
=  $F(\phi(x \otimes f)\phi(x \otimes f) + \phi(x \otimes f)\phi(x \otimes f))$   
=  $F(y \otimes gy \otimes g + y \otimes gy \otimes g)$   
=  $F(2g(y)y \otimes g).$ 

Thus we get that  $2g(y)^2 = 1$  and  $span\{x\} = span\{y\}$ .

Without loss of generality, we may assume that  $\phi(x \otimes f) = x \otimes g_{x,f}$ where  $g_{x,f} \in X^*$ .

Now, suppose that f and  $g_{x,f}$  are linearly independent. Let  $z \in X$  be a nonzero vector such that x and z are linearly independent with  $f(z) = \frac{1}{\sqrt{2}}$  and  $g_{x,f}(z) = 0$ , then  $x + z \in F(x \otimes fz \otimes f + z \otimes fx \otimes f)$ . On the other hand we have

$$F(x \otimes fz \otimes f + z \otimes fx \otimes f) = F(\phi(x \otimes f)\phi(z \otimes f) + \phi(z \otimes f)\phi(x \otimes f))$$
  
=  $F(x \otimes g_{x,f}z \otimes g_{z,f} + z \otimes g_{z,f}x \otimes g_{x,f})$   
=  $F(g_{z,f}(x)z \otimes g_{x,f})$   
=  $\{0\},$ 

which is a contradiction. Hence  $g_{x,f}$  and f are linearly dependent, thus  $\phi(x \otimes f) = \lambda_{x,f} x \otimes f$  for some nonzero scalar  $\lambda_{x,f}$ . Therefore, there exists

a nonzero scalar  $\lambda_A \in \mathbf{C}$  such that  $\phi(A) = \lambda_A A$  for all  $A \in \mathcal{F}_{1,\sqrt{2}}(X)$ . It follows from this that

(3.3) 
$$F(AA + AA) = F(\phi(A)\phi(A) + \phi(A)\phi(A))$$
$$= F(\lambda_A^2(AA + AA)).$$

by (3.3) and the fact that  $F(AA + AA) \neq \{0\}$ , we obtain that  $\lambda_A^2 = 1$ . Now, let  $x \in X$  be a nonzero vector and pick  $f \in X^*$  such that  $f(x) = \frac{1}{\sqrt{2}}$ . For  $A = x \otimes f$ , we have

$$\left(\frac{1}{\sqrt{2}}IA + \frac{1}{\sqrt{2}}AI\right)x = x$$

and so

(3.4) 
$$(\lambda_A \phi(\frac{1}{\sqrt{2}}I)A + \lambda_A A \phi(\frac{1}{\sqrt{2}}I))x = x.$$

This proves that  $\phi(\frac{1}{\sqrt{2}}I)x$  and x are linearly dependent for all  $x \in X$ . Hence  $\phi(\frac{1}{\sqrt{2}}I)$  and I are linearly dependent. Thus, from (3.4) we easily get that there exists a nonzero scalar  $\alpha \in \mathbf{C}$  such that  $\phi(\frac{1}{\sqrt{2}}I) = \alpha \frac{1}{\sqrt{2}}I$  and we have  $\lambda_A = \alpha$ . We conclude that  $\phi(A) = \alpha A$  for every  $A \in \mathcal{F}_{1,\sqrt{2}}(X)$  with  $\alpha^2 = 1$ , as desired.

**Step 4.**  $\phi$  takes the desired form.

Let  $\alpha$  be the nonzero scalar in Step 3. For every  $A \in \mathcal{F}_{1,\sqrt{2}}(X)$  and  $T \in \mathcal{B}(X) \setminus \mathbf{C}.I$ , we have

$$F(TA + AT) = F(\phi(T)\phi(A) + \phi(A)\phi(T))$$
  
=  $F(\alpha\phi(T)A + \alpha A\phi(T)).$ 

Lemma 1 ensures that  $\phi(T) = \alpha T$  for all  $T \in \mathcal{B}(X) \setminus \mathbf{C}.I$ .

Now, if  $T = \gamma I$  where  $\gamma$  is a nonzero scalar. Consider an operator  $A = x \otimes f$  such that  $f(x) = \frac{1}{2\gamma}$ . Since A is a non-scalar operator, then  $\phi(A) = \alpha A$ . Just as in Step 3 when  $\gamma = \frac{1}{\sqrt{2}}$ , we obtain that  $\phi(\gamma I) = \alpha \gamma I$ .

Therefore, we conclude that  $\phi(T) = \alpha T$  for every  $T \in \mathcal{B}(X)$ .

**Acknowledgement.** The authors would like to thank the referee for carefully reading this paper and the helpful comments.

### References

- A. Achchi, "Maps preserving the inner local spectral radius zero of generalized product of operators", *Rendiconti del Circolo Matematico di Palermo Series 2*, vol. 68, no. 2, pp. 355-362, 2018. doi: 10.1007/s12215-018-0363-9
- Y. Bouramdane, M. Ech-cherif El Kettani, A. Elhiri, and A. lahssaini, "Maps preserving fixed points of generalized product of operators", *Proyecciones (Antofagasta)*, vol. 39, no 5, pp. 1157-1165, 2020. doi: 10.22199/issn.0717-6279-2020-05-0071
- [3] G. Dolinar, S. Du, J. Hou, and P. Legia, "General preservers of invariant subspace lattices", *Linear algebra and its applications*, vol. 429, no 1, pp. 100-109, 2008. doi: 10.1016/j.laa.2008.02.007
- [4] M. Elhodaibi and S. Elouazzani, "Jordan product and inner local spectral radius", *Preprint*.
- [5] A. Guterman, C.-K. Li, and P. Semrl, "Some general techniques on linear preserver problems", *Linear Algebra and its Applications*, vol. 315, no 1-3, pp. 61-81, 2000. doi: 10.1016/s0024-3795(00)00119-1
- [6] A. A. Jafarian and A. R. Sourour, "Linear maps that preserve the com-mutant, double commutant or the lattice of invariant subspaces", *Linear and multilinear algebra*, vol. 38, no. 1-2, pp. 117-129, 1994. doi: 10.1080/03081089508818345
- [7] C. K. Li, P. Semrl and N. S. Sze, "Maps preserving the nilpotency of products of operators", *Linear algebra and its applications*, vol. 424, no 1, pp. 222-239, 2007. doi: 10.1016/j.laa.2006.11.013
- [8] C. K. Li, and N. K. Tsing, "Linear preserver problems: A brief introduction and some special techniques", *Linear algebra and its applications*, vol. 162, pp. 217-235, 1992. doi: 10.1016/0024-3795(92)90377-m
- [9] A. Taghavi and R. Hosseinzadeh, "Maps preserving the dimension of fixed points of products of operators", *Linear and multilinear algebra*, vol. 62, no. 10, pp. 1285-1292, 2013. doi: 10.1080/03081087.2013.823680
- [10] A. Taghavi, R. Hosseinzadeh, and V. Darvish, "Maps preserving the fixed points of triple Jordan products of operators", *Indagationes mathematicae*, vol. 27, no. 3, pp. 850-854, 2016. doi: 10.1016/j.indag.2016.03.003

### M. Elhodaibi

Departement of Mathematics, Labo LIABM, Faculty of Sciences, 60000 Oujda, Morocco e-mail: elhodaibi@ump.ac.ma Corresponding author

and

### S. Elouazzani

Departement of Mathematics, Labo LIABM, Faculty of Sciences, 60000 Oujda, Morocco e-mail: elouazzani.soufiane@ump.ac.ma