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ON A NEW ITERATION FOR SOLVING CHANDRASEKHAR'S H-EQUATION

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Abstract.

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A new iteration for solving Chandrasekhar's H-Equation is given. Under certain assumptions the iteration converges without the usual positi vity assumptions on the parameters involved.

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Introduction.

In the theories of radiative transfer [2] and neutron transport [3] an important role is played by nonlinear integral equations of the form

$$H(s) = 1 + \lambda H(s) \int_{0}^{1} k(s,t)H(t)\psi(t)dt.$$
 (1)

In Eq. (1), λ is a real (or complex) parameter, $\psi \in X = L'[0,1]$ es given and real valued, the kernel K(s,t) on XxX satisfies

(i) 0 < K(s,t) < 1, s, t ε X
(ii) K(s,t) + K(t,s) = 1, s, t ε X.

and H is the function to be found.

The question has been answered under certain assumptions on λ (usually $|\lambda| \leq 1$) and positivity assumptions on ψ as in [1], [2], [4], [5] and the reference there.

We introduce a new iteration that converges for any λ for which a solution to Eq. (1) exists and do not require positivity assumptions on ψ and restrictions on λ as in [1], [4], [5].

I. BASIC THEOREMS.

We consider the Banach space C[0,1] of complex valued continuous functions on [0,1] with the supremum norm. We define a bounded linear operator and a bounded bilinear operator \overline{B} [6] or C[0,1] by

22

$$(Lw)(s) = \int_{0}^{1} K(s,t)\psi(t)w(t)dt$$

$$B(w,z)(s) = w(s)(Lz)(s) + z(s)(Lw(s)).$$

Denote by $\overline{B}'(w)$ the Frechet derivative of \overline{B} given by

 $\overline{B}(w)z = wLz + xLw$ for w, z ϵ C[0,1].

Define the linear operator E on a subset D of C[0,1] by

$$E(w) = \int_{0}^{1} w(t)H(t)\psi(t)dt$$

where H is a solution to Eq. 1.

Fact. Let U =
$$\int_{0}^{1} H(t) \psi(t) dt$$
 and $\Psi = \int_{0}^{1} \psi(t) dt$ then U² - 2U + $\Psi = 0$

The proof can be found in [2].

Theorem 1. Let $H = H(\lambda_0)$ be any solution to Eq. (1) with $\lambda = \lambda_0$. If $\int_0^1 \psi(t) dt \neq 0$ and Kern(L) = {0} then $\overline{B}'(H(\lambda_0))$ is an invertible linear operator on C[0,1] with bounded inverse for any λ .

Proof. Let $z \in C[0,1]$ be such that

$$\overline{B}'(H(\lambda_0))z = 0$$

$$0 = \int_0^1 \psi(t)B(H(\lambda_0), z)(t)dt$$

$$= \left[\int_0^1 \psi(t)H(t)dt\right] \int_0^1 z(t)\psi(t)dt$$
Hence either $\int_0^1 z(t)\psi(t)dt = 0$ or $\int_0^1 \psi(t)H(t)dt = 0.$

By the fact before if U = 0 then $\Psi = 0$ which is a contradiction.

If $\int_{0}^{1} z(t)\psi(t)dt = 0$ then

$$E(w) = 0$$
 for $w(t) = H^{-1}(t)z(t)$

and since $Kern(E) = \{0\} \rightarrow w = 0 \rightarrow z = 0$ and the theorem is proved.

We now introduce the iteration

$$H_{n} = H_{n-1} + (\overline{B}(H_{n-1}))^{-1}(H_{n-1} - 1 - \overline{B}(H_{n-1}, H_{n-1})).$$
(2)

Convergence of the above iteration is a consequence of Theorem 1 and Theorem 3 given in part II of this paper. Here to simplify computations as it is suggested in [4] we assume existence of a solution and seek only to show that the solution may be computed by the above iteration.

Theorem 2. Let $H(\lambda_0)$ be a solution to Eq.(1). Then there exists $\epsilon_0 > 0$ such that if

$$||H_0 - H(\lambda_0)|| < \varepsilon_0$$

the iteration scheme given by (2) converges and

$$||H_{n+1} - H(\lambda_0)|| \le || I - (\overline{B}(H(\lambda_0)))^{-1}|| \cdot || H_n - H(\lambda_0)||.$$

Proof. By Theorem 1, $(\overline{B}(H(\lambda_0)))^{-1}$ exist on D. As $\overline{B}(w)$ is continuous in w for fixed $\lambda = \lambda_0$, there exists $\varepsilon > 0$ such that if

$$|| H(\lambda_0) - w || < \epsilon$$
 then $(\overline{B}(w))^{-1}$ exists.

Let $H_0 \epsilon$ C[0,1] be such that

$$||H(\lambda_0) - H_0|| < \varepsilon_0 < \varepsilon$$

We show that if $||H(\lambda_0)-H_n||<\epsilon_0$ and ϵ_0 is sufficiently small then

$$\left|\left|H_{n+1} - H(\lambda_0)\right|\right| < \varepsilon_0.$$

Let $d_n = H_n - H(\lambda_0) ||$ and $H = H(\lambda_0)$, then

$$d_{n+1} = d_n + \overline{B}(H_n))^{-1}(H_{n-1}) - H_n$$

= $d_n + \overline{B}(H(\lambda_0) + d_n)^{-1}[H + d_n - 1 - \overline{B}(H + d_n)(H + d_n)]$
= $(\overline{B}(H + d_n))^{-1}[d_n - \overline{B}(d_n, H)]$
= $[I - \overline{B}(H)^{-1}\overline{B}(-d_n)]^{-1}[\overline{B}(H)^{-1} - I](d_n)$

$$= \sum_{k=0}^{\infty} [\overline{B}(H)^{-1}\overline{B}(-d_{n})]^{k} [\overline{B}(H)^{-1} - I](d_{n})$$
$$= \sum_{k=0}^{\infty} (\overline{B}(H)^{-1}B(-d_{n}))^{k} \overline{B}(H)^{-1}(d_{n})$$
$$- \sum_{k=0}^{\infty} (\overline{B}(H))^{-1} \overline{B}(-d_{n})^{k} (d_{n})$$

By taking norms in the above equation we have

$$||d_{n} + 1|| \leq ||d_{n}|| ||I - \overline{B}(H)^{-1}|| + 0 (||d_{n}||^{2}).$$

If $||d_n|| < \varepsilon_0$ is sufficiently small, we have

$$||d_{n+1}|| \leq ||I - \overline{B}(H)^{-1}|| \cdot ||d_n|| < \varepsilon_0$$

and the theorem is proved.

II. EXISTENCE THEOREMS FOR THE SOLUTION OF THE QUADRATIC EQUATION.

We consider the quadratic equation x = y + B(x,x) in a Banach space X, where $y \in X$ is fixed and B is a bounded bilinear operator on X.

Equation (1) is a special case of Eq. (3) provided that $\lambda \overline{B} = B$, H = x, y = 1 and x = L'[0,1]. We examine the convergence of the iterations

$$X_{n+1} = B(x_n)^{-1}(x_n - y)$$
 or $x_{n+1} = X_n + B(x_n)^{-1}(x_n - y - B(x_n, x_n)).$

Note that in case of convergence, a solution x of equation (3) is obtained.

We now state the following lemma. The proof can be found in [10].

Lemma 1. Let L_1 and L_2 be bounded linear operators in a Banach space X, where L_1 is invertible, and $||L_1^{-1}|| \cdot ||L_2^{-1}| < 1$. Then $(L_1 + L_2^{-1})^{-1}$ exists, and

$$|| (L_1 + L_2)^{-1} || \le \frac{||L_1^{-1}||}{1 - ||L_2|| \cdot ||L_1^{-1}||}$$

Lemma 2. Let $z \neq 0$ be fixed in X. Assume that the linear operator B(z) is invertible then B(x) is also invertible for all $x \in U(z, r) = \{x \in X \mid ||x-z|| < r\}$, where $r \in (0, r_0)$ and $r_0 = [||B|| \cdot ||B(z)^{-1}||]^{-1}$.

Proof. We have

$$||B(x-z)|| \cdot ||B(z)^{-1}|| \le ||B|| \cdot ||x-z|| \cdot ||B(z)^{-1}||$$

 $\leq ||B|| \cdot ||B(z)^{-1}|| \cdot r$

< 1

for $r \in (0, r_0)$. The result now follows from Lemma 1 for $L_1 = B(z)$, $L_2 = B(x-z)$ and $x \in U(z, r)$.

Definition 1. Let $z \neq 0$ be fixed in X. Assume that the linear operator B(z) is invertible.

Define the operators P,T on U(z,r) by

$$P(x) = B(x,x) + y - x, T(x) = (B(x))^{-1}(x-y)$$

. . .

and the real polynomials f(r), g(r) on R by

$$f(r) = a'r^{2} + b'r + c', g(r) = ar^{2} + br + c,$$

$$a' = (||B|| \cdot ||B(z)^{-1}||)$$

$$b' = -2||B|| \cdot ||B(z)^{-1}||$$

$$c' = 1 - ||B(z)^{-1}|| - ||B|| \cdot ||B(z)^{-1}||^{2} \cdot ||z-y||$$

$$a = r_{0}^{-1}$$

$$b = ||B(z)^{-1}(I-B(z))|| - 1$$

$$c = ||B(z)^{-1}P(z)||.$$

From now on we assume that B is a bounded symmetric bilinear operator on $X{\times}X{\mbox{.}}$

Theorem 3. Let $x \in X$ be such that B(z) is invertible and that the following are true:

a) c' > 0; b) b < 0, b² - 4ac > 0, and Then the iteration

$$x_{n+1} = B(x_n)^{-1}(x_n - y), \quad n = 0, 1, 2, \dots$$

is well defined and it converges to a unique solution x in $\overline{U}(z,r)$ of (3) for any $x_0 \in \overline{U}(z,r)$.

Proof. T is well defined by lemma 2.

Claim 1. T maps $\overline{U}(z,r)$ into $\overline{U}(z,r)$.

If $x \in \overline{U}(z,r)$ then

 $T(x) - z = B(x)^{-1}(x-y) - z$

$$= B(x)^{-1}[(I - B(z)) (x-z) - P(z)]$$

so

$$\frac{1}{1 - ||B|| \cdot ||B(z)^{-1}||r} [||B(z)^{-1}(I - B(z))||r + ||B(z)^{-1}P(z)||] \le r$$

(using lemma 1 for $L_1 = B(z)$ and $L_2 = B(x-z)$) or $g(r) \le 0$ which is true by hypothesis.

Claim 2. T is a contraction operator on $\overline{U}(z,r)$.

If w, v $\in \overline{U}(z, r)$ then

$$\begin{split} ||T(w) - T(v)|| &= ||B(w)^{-1}(w-y) - B(v)^{-1}(v-y)|| = ||B(w)^{-1}[I - B(B(v)^{-1}(v-y)](w-v)|| \\ &= ||B(w)^{-1}[I - B(B(v)^{-1}(v-z)) + B(B(v)^{-1}(z-y))](w-v)|| \\ \leq & \underbrace{||B(w)^{-1}[I - B(B(v)^{-1}(v-z)] + B(B(v)^{-1}(z-y))](w-v)||}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot ||B(z)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot r} \int ||W-v|| \cdot r \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r}_{1-||B|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}|| \cdot r} \int ||W-v|| \\ \leq & \underbrace{||B(v)^{-1}$$

= q • | |w-v | |

So T is a contraction on $\overline{U}(z{\mathchar`-}r)$ if 0 < q < 1, where

$$q = \frac{1}{1 - ||B|| \cdot ||B(z)^{-1}|| \cdot r} \left[\frac{||B(z)^{-1}|| + \frac{||B|| \cdot ||B(z)^{-1}||^2_r + ||B||||B(z)^{-1}||^2_r + ||B|||B(z)^{-1}||^2_r + ||B|||B(z)^{-1}||B|||B(z)^{-1}||B|||B(z)^{-1}||^2_r + ||B|||B(z)^{-1}||^2_r + ||$$

-

which is true since f(r) > 0.

Note that Theorems 1 and 3 can now be used to compute the solution to Eq. (1) by iteration (4), if z = H and $\overline{U}(H,r) \subset D$.

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